

# Morse-Bott Flows and Cut Locus of Submanifolds

(based on joint work with Dr. Somnath Basu)

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# Outline of the talk

- 1 Geometric aspects of the cut locus
- 2 Topological aspects of the cut locus

# Geometric aspects of the cut locus

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The  $\text{Hess}_p(f)$  is **non-degenerate in the direction normal to  $N$  at  $p$**  means for any  $V \in (T_p N)^\perp$  there exists  $W \in (T_p N)^\perp$  such that  $\text{Hess}_p(f)(V, W) \neq 0$ .

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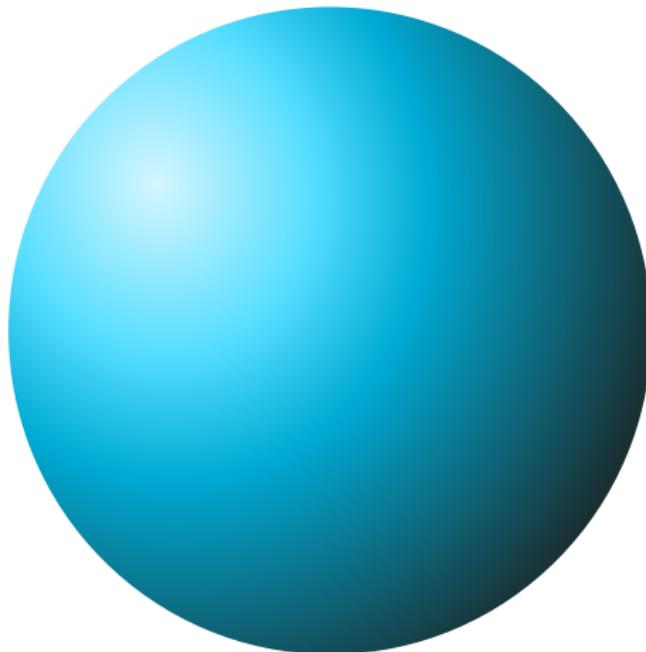
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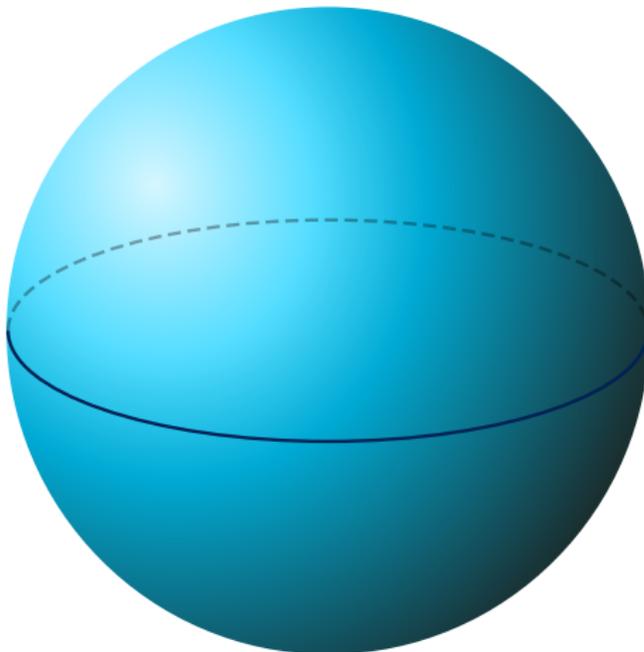
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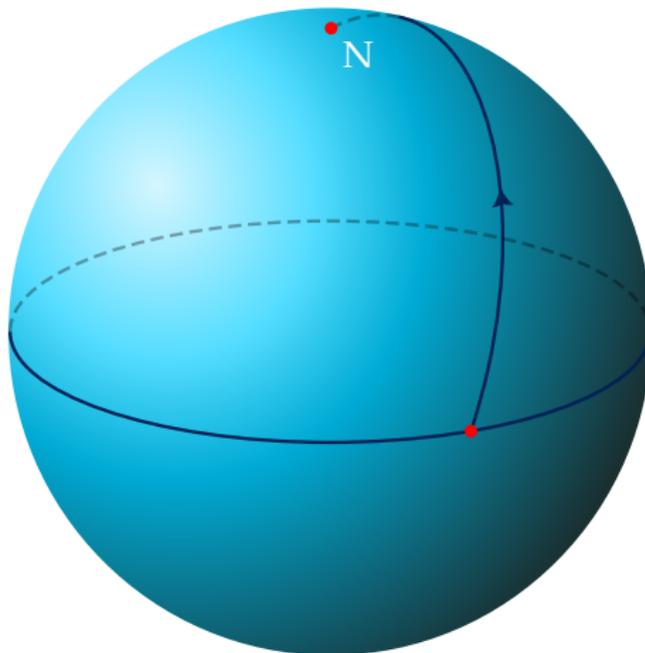
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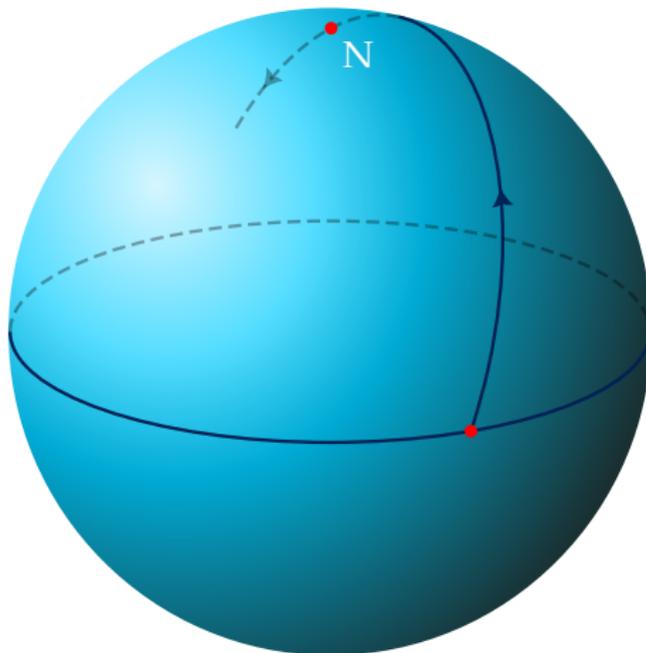
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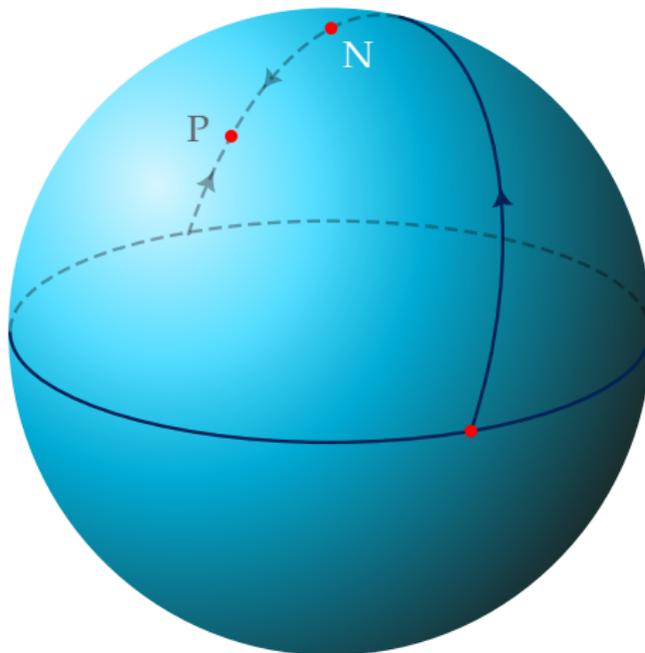
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## Theorem (Basu S., Prasad S., 2021)

*For a complete Riemannian manifold  $M$  and a compact submanifold  $N$  of  $M$ ,*

$$\overline{\text{Se}(N)} = \text{Cu}(N).$$

# An illuminating example

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Let  $M = M(n, \mathbb{R})$ , the set of  $n \times n$  matrices, and  $N = O(n, \mathbb{R})$ , set of all orthogonal  $n \times n$  matrices.

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Consider the distance squared function

$$f : M(n, \mathbb{R}) \rightarrow \mathbb{R}, \quad A \mapsto d^2(A, O(n, \mathbb{R})).$$

- The function is  $f(A) = n + \text{tr}(A^T A) - 2\text{tr}(\sqrt{A^T A})$ .
- It is differentiable at  $A$  if and only if  $A$  is invertible.
- It is a Morse-Bott function with critical submanifold as  $O(n, \mathbb{R})$ .
- If  $\gamma(t)$  is an integral curve of  $-\nabla f$  initialized at  $A$ , then

$$\frac{d\gamma}{dt} = -2\gamma(t) + 2(\gamma(t)^T)^{-1} \sqrt{\gamma(t)^T \gamma(t)}. \quad (1)$$

- The solution of (1) given by

$$\gamma(t) = Ae^{-2t} + (1 - e^{-2t})A(\sqrt{A^T A})^{-1}, \quad \gamma(0) = A. \quad (2)$$

- The flow line  $\gamma(t)$  deforms  $GL(n, \mathbb{R})$  to  $O(n, \mathbb{R})$ .
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Define

$$\mathbf{s} : S(\nu) \rightarrow [0, \infty], \mathbf{s}(v) := \sup\{t \in [0, \infty) \mid \gamma_v|_{[0,t]} \text{ is an } N\text{-geodesic}\},$$

where  $S(\nu)$  is the unit normal bundle of  $N$  and  $[0, \infty]$  is the one-point compactification of  $[0, \infty)$ .

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where  $S(\nu)$  is the unit normal bundle of  $N$  and  $[0, \infty]$  is the one-point compactification of  $[0, \infty)$ . The map  $\mathbf{s}$  is continuous and is finite if  $M$  is compact.

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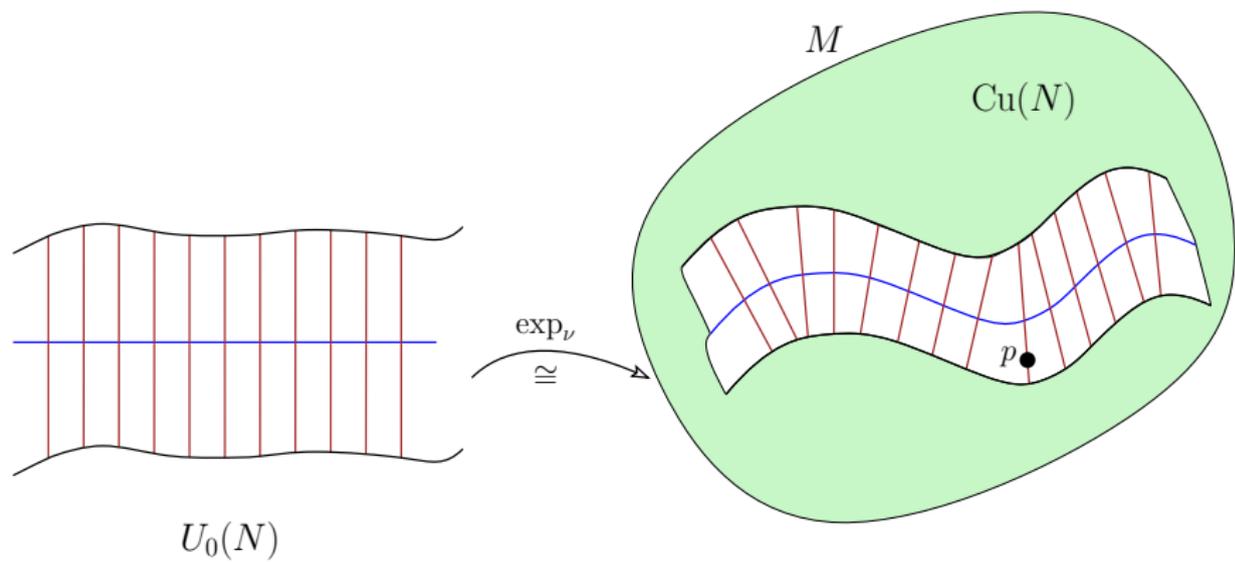
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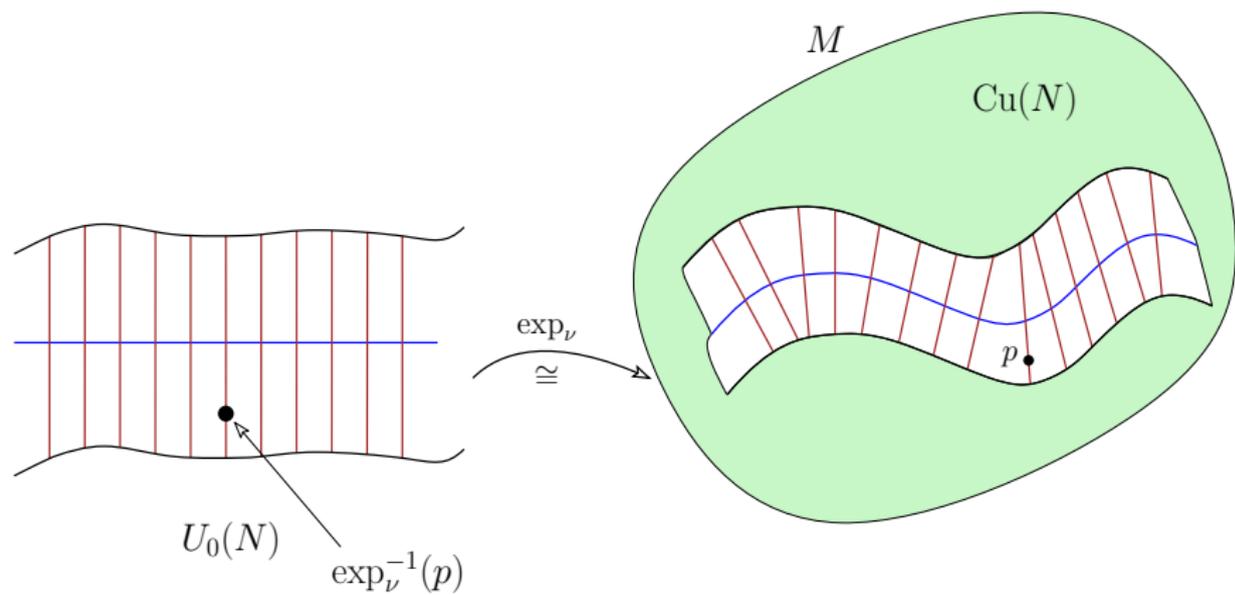
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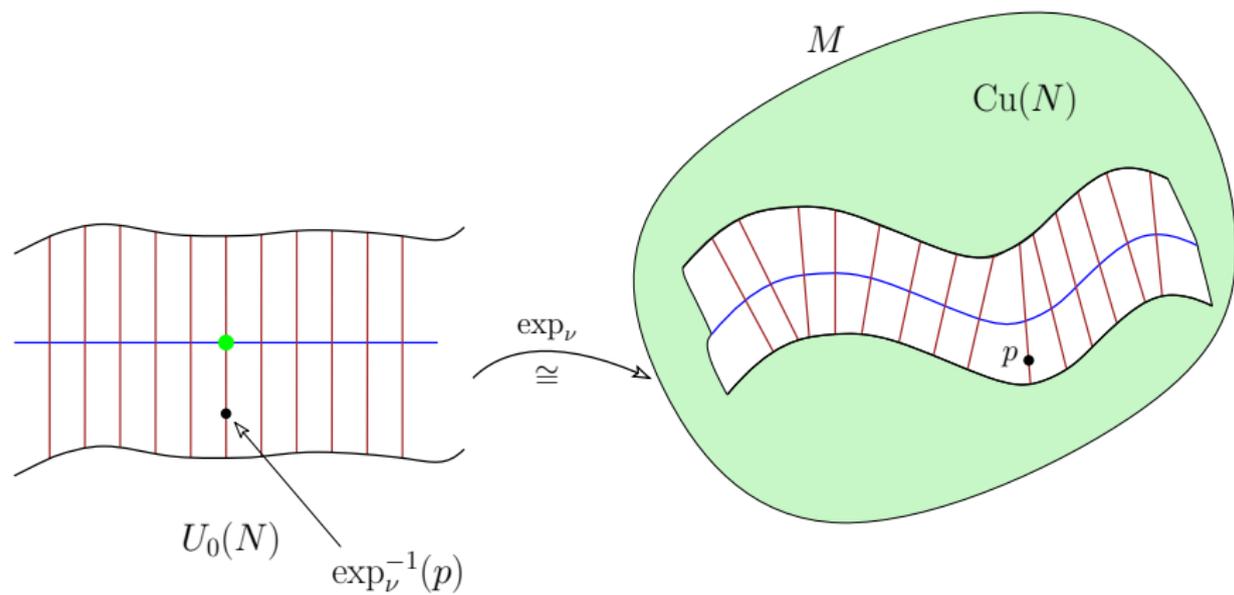
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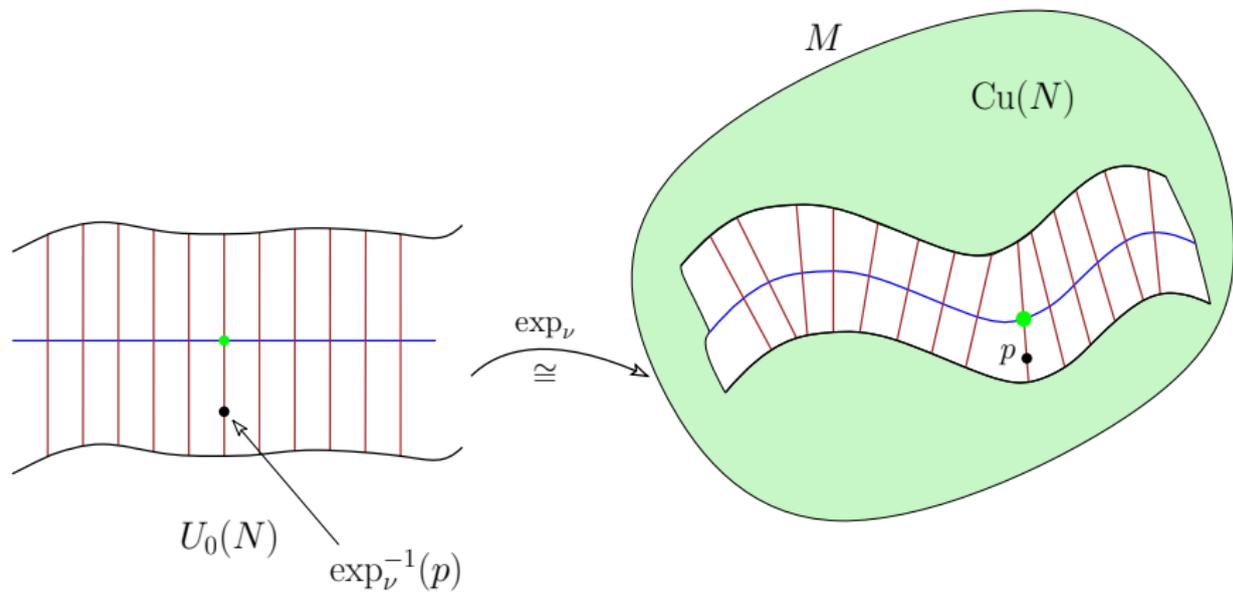
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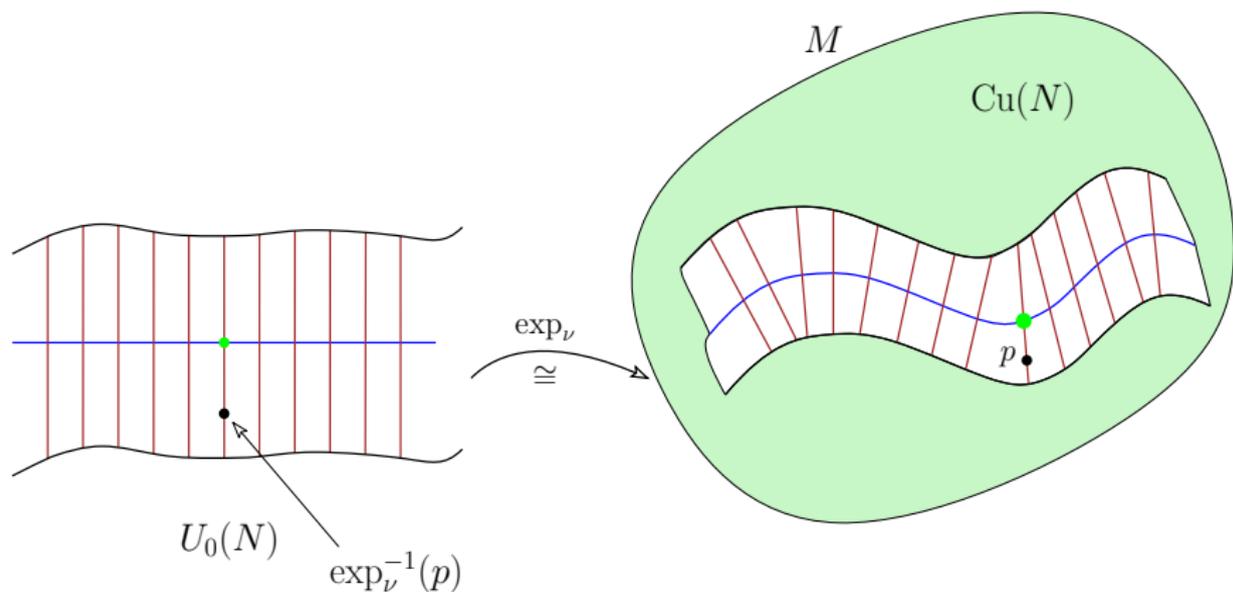
Note that  $\exp_\nu$  is a diffeomorphism on  $U_0(N)$  and set  $U(N) = \exp_\nu(U_0(N)) = M - \text{Cu}(N)$ .



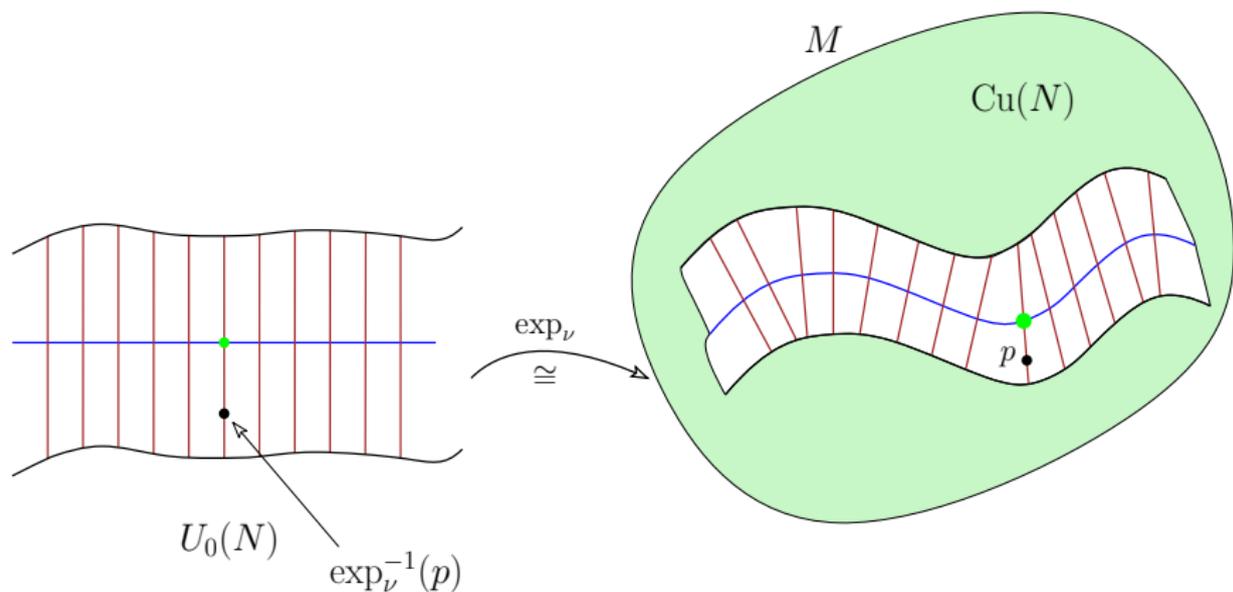








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$$H : U_0(N) \times [0, 1] \rightarrow U_0(N), ((p, av), t) \mapsto (p, tav).$$

Now consider the following diagram:

$$\begin{array}{ccc}
 U_0(N) \times [0, 1] & \xrightarrow{H} & U_0(N) \\
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The map  $F$  can be defined by taking the compositions

$$F = \exp_\nu \circ H \circ \exp_\nu^{-1}.$$

# Topological aspects of the cut locus

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## Remark

If  $B$  is compact, then  $\text{Th}(E)$  is the one point compactification of  $E$ .

## Definition (Rescaled exponential)

The *rescaled exponential* map is defined to be

$$\widetilde{\exp} : D(\nu) \rightarrow M, (p, v) \mapsto \begin{cases} \exp_p(\mathbf{s}(\hat{v})v), & \text{if } v = \|v\|\hat{v} \\ p, & \text{if } v = 0. \end{cases}$$

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Since  $\mathbf{s}$  is continuous, the rescaled exponential is also continuous and is surjective. Also note that  $\widetilde{\exp}(S(\nu)) = \text{Cu}(N)$ .

# The Main Theorem

Theorem (Basu S., Prasad S., 2021)

*Let  $N$  be an embedded submanifold inside a closed, connected Riemannian manifold  $M$ . If  $\nu$  denotes the normal bundle of  $N$  in  $M$ , then there is a homeomorphism*

$$\widetilde{\text{exp}} : D(\nu)/S(\nu) \xrightarrow{\cong} M/\text{Cu}(N).$$

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- Let  $N$  be a smooth homology  $k$ -sphere,  $k > 0$ , embedded in a smooth Riemannian manifold  $M$  homeomorphic to  $S^d$ . If  $d \geq k + 3$ , then the cut locus  $\text{Cu}(N)$  is homotopy equivalent to  $S^{d-k-1}$ .

Thank You for your attention!